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Graph partitioning algorithms

Network Science

Lecture 7

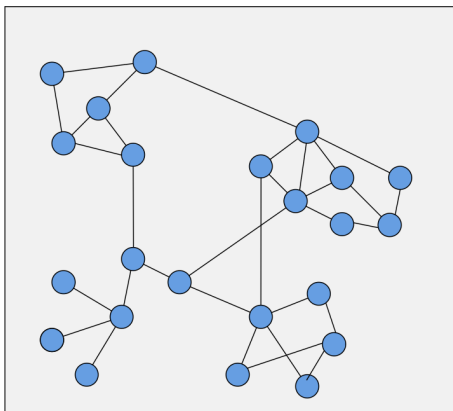
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Graph partitioning is the split of a graph into subgraphs by partitioning its set of nodes into mutually exclusive groups



- Exact solution NP-hard
- Number of ways to divide network of n nodes in 2 groups (bi-partition): $2^{n-1} - 1$ ways - distinct cuts
- Combinatorial optimization problem:
 - optimization criterion
 - optimization method
- Solved by greedy, approximate algorithms or heuristics
- Balanced vs unbalanced partition
- 2 way-partition vs multiway partition

- Greedy optimization:
Local search [Kernighan and Lin, 1970], [Fiducia and Mettheyses, 1982]
- Approximate optimization:
Spectral graph partitioning [M. Fiedler, 1972], [Pothen et al 1990], [Shi and Malik, 2000]
Multicommodity flow [Leighton and Rao, 1988]
- Randomized algorithms:
Randomized min cut [D. Karger, 1993]
- Heuristics algorithms:
Multilevel graph partitioning (METIS) [G. Karypis, Kumar 1998]

Graph $G(E, V)$ partition: $V = V_1 + V_2$

- Graph cut

$$Q = \text{cut}(V_1, V_2) = \sum_{i \in V_1, j \in V_2} e_{ij}$$

- Ratio cut:

$$Q = \frac{\text{cut}(V_1, V_2)}{||V_1||} + \frac{\text{cut}(V_1, V_2)}{||V_2||}$$

- Normalized cut:

$$Q = \frac{\text{cut}(V_1, V_2)}{\text{Vol}(V_1)} + \frac{\text{cut}(V_1, V_2)}{\text{Vol}(V_2)}$$

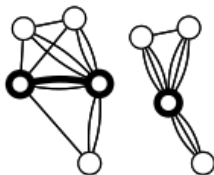
- Quotient cut (conductance):

$$Q = \frac{\text{cut}(V_1, V_2)}{\min(\text{Vol}(V_1), \text{Vol}(V_2))}$$

where: $\text{Vol}(V_1) = \sum_{i \in V_1, j \in V} e_{ij} = \sum_{i \in V_1} k_i$

Karger's algorithm for finding minimum cut

- Edge contraction - removing an edge and merging two vertices that it previously joined



- $P(\text{final cut} = \text{mincut}) \geq 2/n^2$
- Run it $\Omega(n^2)$ times and choose the smallest cut

Input: Graph G

Output: class indicator vector $mincutX$

$X = \text{inf}$

for $i = 1 : N$

$X = \text{GuessMinCut}(G)$

 if $|X| < mincutk$

$mincutX = X, mincutk = |X|$

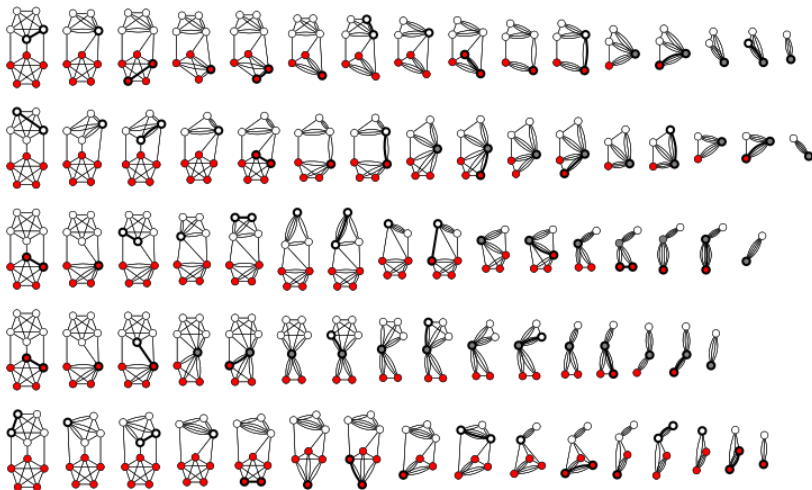
return $mincutX$

for $i = N$ down to 2

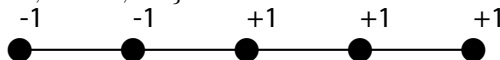
 pick a random edge e in G

$G = G/e$

return the only cut in G



- Let $V = V^+ + V^-$ be partitioning of the nodes
- Let $\mathbf{s} = \{+1, -1, +1, \dots, -1, +1\}^T$ - indicator vector



$$s(i) = \begin{cases} +1 : & \text{if } v(i) \in V^+ \\ -1 : & \text{if } v(i) \in V^- \end{cases}$$

- Number of edges, connecting V^+ and V^-

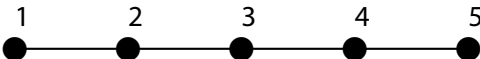
$$\begin{aligned} cut(V^+, V^-) &= \frac{1}{4} \sum_{e(i,j)} (s(i) - s(j))^2 = \frac{1}{8} \sum_{i,j} A_{ij} (s(i) - s(j))^2 = \\ &= \frac{1}{4} \sum_{i,j} (k_i \delta_{ij} s(i)^2 - A_{ij} s(i) s(j)) = \frac{1}{4} \sum_{i,j} (k_i \delta_{ij} - A_{ij}) s(i) s(j) \end{aligned}$$

$$cut(V^+, V^-) = \frac{1}{4} \sum_{i,j} (D_{ij} - A_{ij}) s(i) s(j)$$

- Graph Laplacian: $\mathbf{L}_{ij} = \mathbf{D}_{ij} - \mathbf{A}_{ij}$, where $\mathbf{D}_{ii} = \text{diag}(k_i)$

$$\mathbf{L}_{ij} = \begin{cases} k(i), & \text{if } i = j \\ -1, & \text{if } \exists e(i, j) \\ 0, & \text{otherwise} \end{cases}$$

- Laplacian matrix 5x5:

$$\mathbf{L} = \begin{pmatrix} 1 & -1 & & & \\ -1 & 2 & -1 & & \\ & -1 & 2 & -1 & \\ & & -1 & 2 & -1 \\ & & & -1 & 1 \end{pmatrix}$$


A path graph with 5 nodes labeled 1 to 5 connected in a line.

- Graph Laplacian: $\mathbf{L} = \mathbf{D} - \mathbf{A}$
- Graph cut:

$$Q(\mathbf{s}) = \text{cut}(V^+, V^-) = \frac{1}{4} \sum_{ij} L_{ij} s(i) s(j) = \frac{\mathbf{s}^T \mathbf{L} \mathbf{s}}{4}$$

- Minimal cut:

$$\min_{\mathbf{s}} Q(\mathbf{s})$$

- Balanced cut constraint:

$$\sum_i s(i) = 0$$

- Integer minimization problem, exact solution is NP-hard!

- Discrete problem $\rightarrow$ continuous problem
- Discrete problem: find

$$\min_{\mathbf{s}} \left(\frac{1}{4} \mathbf{s}^T \mathbf{L} \mathbf{s} \right)$$

under constraints: $s(i) = \pm 1, \sum_i s(i) = 0$;

- Relaxation - continuous problem: find

$$\min_{\mathbf{x}} \left(\frac{1}{4} \mathbf{x}^T \mathbf{L} \mathbf{x} \right)$$

under constraints: $\sum_i x(i)^2 = n, \sum_i x(i) = 0$

- Given $x(i)$, round them up by $s(i) = \text{sign}(x(i))$
- Exact constraint satisfies relaxed equation, but not other way around!

- Constraint optimization problem (Lagrange multipliers):

$$Q(\mathbf{x}) = \frac{1}{4} \mathbf{x}^T \mathbf{L} \mathbf{x} - \lambda (\mathbf{x}^T \mathbf{x} - n), \quad \mathbf{x}^T \mathbf{e} = 0$$

- Eigenvalue problem:

$$\mathbf{L} \mathbf{x} = \lambda \mathbf{x}, \quad \mathbf{x} \perp \mathbf{e}$$

- Solution:

$$Q(\mathbf{x}_i) = \frac{n}{4} \lambda_i$$

- First (smallest) eigenvector:

$$\mathbf{L} \mathbf{e} = 0, \quad \lambda = 0, \quad \mathbf{x}_1 = \mathbf{e}$$

- Looking for the second smallest eigenvalue/eigenvector λ_2 and $\mathbf{x}_2$
- Minimization of Rayleigh-Ritz quotient:

$$\min_{\mathbf{x} \perp \mathbf{x}_1} \left(\frac{\mathbf{x}^T \mathbf{L} \mathbf{x}}{\mathbf{x}^T \mathbf{x}} \right)$$

Algorithm: Spectral graph partitioning - normalized cuts

Input: adjacency matrix $\mathbf{A}$

Output: class indicator vector $\mathbf{s}$

compute $\mathbf{D} = \text{diag}(\text{deg}(\mathbf{A}))$;

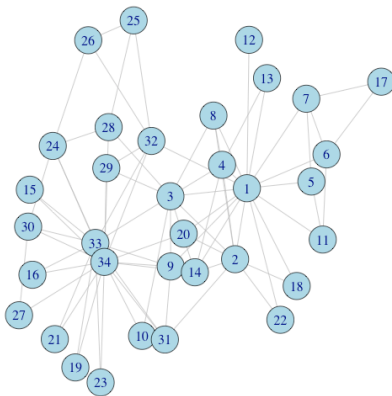
compute $\mathbf{L} = \mathbf{D} - \mathbf{A}$;

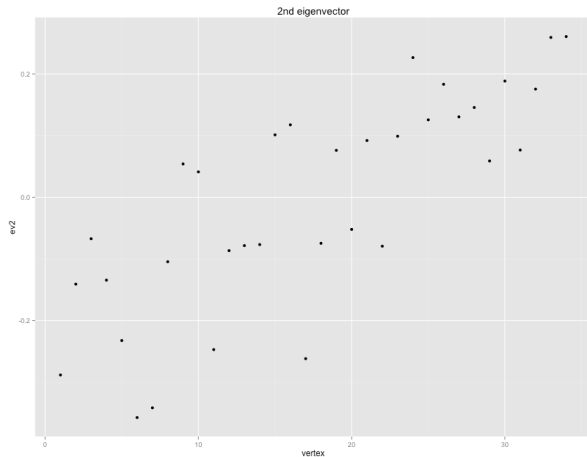
solve for second smallest eigenvector:

min cut: $\mathbf{L}\mathbf{x} = \lambda\mathbf{x}$;

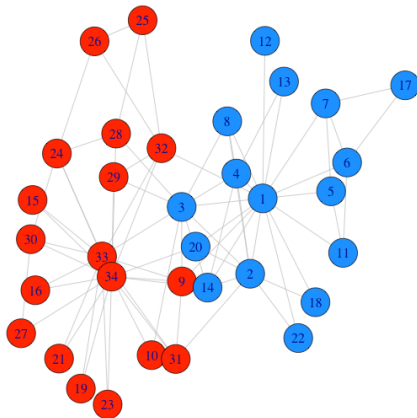
normalized cut : $\mathbf{L}\mathbf{x} = \lambda\mathbf{D}\mathbf{x}$;

set $\mathbf{s} = \text{sign}(\mathbf{x}_2)$

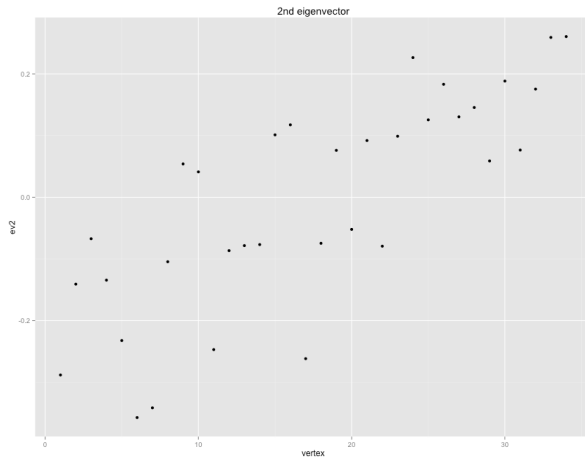


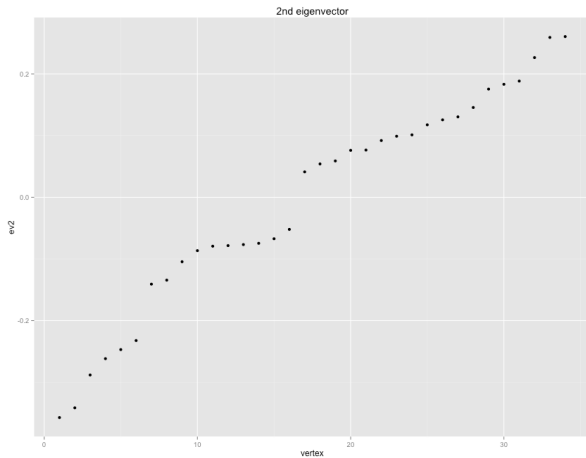


Eigenvalues: $\lambda_1 = 0$, $\lambda_2 = 0.2$, $\lambda_3 = 0.25 \dots$

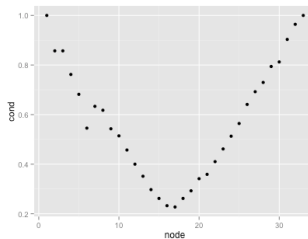
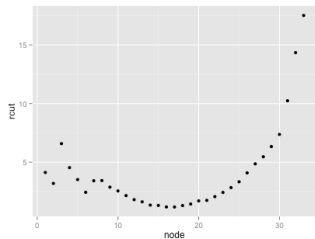
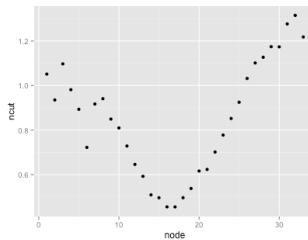
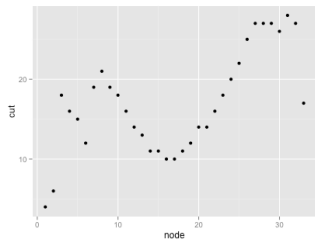


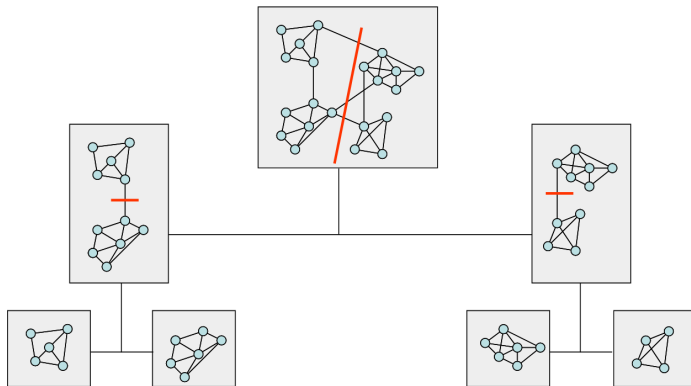
Example



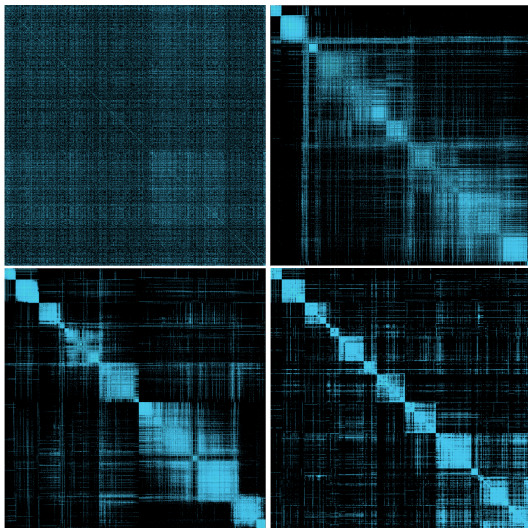


Graph cut metrics





recursive partitioning



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